

Let  $Y_1, \dots, Y_n$  be a fundamental set of solutions of  $Y' = P(t)Y$ .

(Fundamental Matrix)  
 $\Phi = [Y_1 \ Y_2 \ \dots \ Y_n]_{n \times n}$

( $W = |\Phi| \neq 0$ )

Show  $\Phi' = P(t) \cdot \Phi$

∵ Since  $Y_1, \dots, Y_n$  are fundamental solutions

$Y_1' = P Y_1, Y_2' = P Y_2, \dots, Y_n' = P Y_n$

$$\Phi' = [Y_1 \ Y_2 \ \dots \ Y_n]'_{n \times n}$$

$$= [Y_1' \ Y_2' \ \dots \ Y_n']_{n \times n}$$

$$= [P Y_1 \ P Y_2 \ \dots \ P Y_n]_{n \times n}$$

$$= P [Y_1 \ Y_2 \ \dots \ Y_n]$$

# I-Sect 4.8 Variation of Parameters Method

## Sec 4.8: Nonhomogeneous 1st Order Linear Systems.

Has the form standard form

$$\vec{Y}' = P(t) \cdot \vec{Y} + \vec{G}(t), \quad \vec{Y}(t_0) = Y_0, \quad a < t < b$$

Example:

$$\vec{Y}' = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \vec{Y} + \begin{bmatrix} e^t \\ 0 \end{bmatrix}, \quad \vec{Y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

How to solve this type of system?

**Variation of Parameters Method:** First solve the homogeneous problem

$$\vec{Y}' = P(t) \cdot \vec{Y}$$

Let  $\vec{Y}_c(t)$  be the homogeneous solution; i.e.,  $\vec{Y}_c(t) = \Phi(t)\mathbf{c}$  where  $\Phi(t)$  is a fundamental matrix for the homogeneous equation and  $\mathbf{c}$  is an arbitrary  $n \times 1$  column vector.

Now suppose that there is a particular solution for the nonhomogeneous equation that has the form

$$\vec{Y}_p(t) = \Phi(t)\mathbf{u}(t)$$

where  $\mathbf{u}(t)$  is an  $n \times 1$  column vector. Then,  $\vec{Y}_p' = P(t) \cdot \vec{Y}_p + \vec{G}(t)$  and so

$$\Phi'(t)\mathbf{u}(t) + \Phi(t)\mathbf{u}'(t) = P(t)\Phi(t)\mathbf{u}(t) + \vec{G}(t).$$

Since  $\Phi(t)$  is a fundamental matrix for the homogeneous system, we have  $\Phi'(t) = P(t) \cdot \Phi(t)$ . This yields

$$\Phi(t)\mathbf{u}'(t) = \vec{G}(t).$$

Hence the column vector  $\mathbf{u}(t)$  must be  $\int [\Phi(t)]^{-1} \cdot \vec{G}(t) dt$ .

Under the above assumptions we have the following algorithm:

- The non homogeneous system must be given in standard form.
- Identify the matrix  $P(t)$  and the column vector  $\vec{G}(t)$ .
- Find a fundamental matrix  $\Phi(t)$  for the homogeneous system  $\vec{Y}' = P(t) \cdot \vec{Y}$ .
- Compute the inverse of  $\Phi(t)$ .
- Compute the product  $[\Phi(t)]^{-1} \cdot \vec{G}(t)$ .
- Set  $\mathbf{u}(t) = \int [\Phi(t)]^{-1} \cdot \vec{G}(t) dt$ .
- Set  $\vec{Y}_p(t) = \Phi(t)\mathbf{u}(t)$ .
- The general solution to the nonhomogeneous problem is given by  $\vec{Y}(t) = \vec{Y}_c(t) + \vec{Y}_p(t)$ .

$$\textcircled{1} Y_c = \Phi \mathbf{c}$$

$$\textcircled{2} Y_p = \Phi \cdot \mathbf{u}$$

$$\textcircled{3} \text{ Plug } Y_p \text{ into } Y' = PY + G$$

$$(\Phi \mathbf{u})' = P(\Phi \mathbf{u}) + G$$

$$\text{(Product rule)} \quad \Phi' \cdot \mathbf{u} + \Phi \cdot \mathbf{u}' = P \cdot \Phi \mathbf{u} + G$$

$$(\cancel{P \cdot \Phi}) \mathbf{u} + \Phi \mathbf{u}' = P \cdot \cancel{\Phi} \mathbf{u} + G$$

$$\Phi \mathbf{u}' = G$$

$$\mathbf{u}' = \underbrace{\Phi^{-1}} G$$

$$\mathbf{u} = \int \Phi^{-1} G dt$$

DNF

- Set  $Y_p(t) = \Phi(t)\mathbf{u}(t)$ .
- The general solution to the nonhomogeneous problem is given by  $\vec{Y}(t) = \vec{Y}_c(t) + \vec{Y}_p(t)$ .
- Finally, use the initial conditions to get the solution to the i.v.p.

Ex1: Solve the i.v.p.

No Restriction

$$\vec{Y}' = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \vec{Y} + \begin{bmatrix} e^t \\ 0 \end{bmatrix}, \quad \vec{Y}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

(By variation of parameters)

①  $Y_c$ : soln of  $Y' = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} Y'$

Eigenpair:  $(\lambda_1 = -1, \begin{bmatrix} 1 \\ -1 \end{bmatrix}), (\lambda_2 = 3, \begin{bmatrix} 1 \\ 1 \end{bmatrix})$

Two soln:  $Y_1 = e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}, Y_2 = e^{3t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$Y_c = C_1 Y_1 + C_2 Y_2$$

②  $\Phi, \Phi^{-1}$

$$\Phi = \begin{bmatrix} e^{-t} & e^{3t} \\ -e^{-t} & e^{3t} \end{bmatrix}$$

$$\Phi^{-1} = \frac{1}{|\Phi|} \begin{bmatrix} e^{3t} & -e^{3t} \\ e^{-t} & e^{-t} \end{bmatrix}$$

$$|\Phi| = e^{2t} + e^{2t} = 2e^{2t}$$

$$\frac{1}{e^{2t}} = e^{-2t} = \frac{1}{2e^{2t}} \begin{bmatrix} e^{3t} & -e^{3t} \\ e^{-t} & e^{-t} \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} e^t & -e^t \\ e^{-3t} & e^{-3t} \end{bmatrix}$$

③  $= \frac{1}{2} \int \begin{bmatrix} e^{2t} & -e^t \\ e^{-2t} & e^{-3t} \end{bmatrix} \begin{bmatrix} e^t \\ 0 \end{bmatrix} dt$

$$G = \begin{bmatrix} e^t \\ 0 \end{bmatrix}$$

$$= \frac{1}{2} \int \begin{bmatrix} e^{2t} \\ e^{-2t} \end{bmatrix} dt$$

$$= \frac{1}{2} \left[ \int e^{2t} dt \right] = \frac{1}{2} \begin{bmatrix} \frac{1}{2} e^{2t} \\ -\frac{1}{2} e^{2t} \end{bmatrix} = \frac{1}{4} \begin{bmatrix} e^{2t} \\ -e^{2t} \end{bmatrix} \quad \text{u''}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1}$$

$$A^{-1} = \frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\begin{aligned} \textcircled{4} \quad Y_p &= \Phi^{-1} \cdot u \\ &= \frac{1}{4} \begin{bmatrix} e^{-t} & e^{3t} \\ -e^{-t} & e^{3t} \end{bmatrix} \begin{bmatrix} e^{2t} \\ -e^{-2t} \end{bmatrix} = \frac{1}{4} \begin{bmatrix} e^t - e^t = 0 \\ -e^t - e^t = -2e^t \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ -\frac{1}{2}e^t \end{bmatrix} \end{aligned}$$

⑤ General Sol $_{4}$

$$Y = Y_c + Y_p = C_1 \begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix} + C_2 \begin{bmatrix} e^{3t} \\ e^{3t} \end{bmatrix} + \begin{bmatrix} 0 \\ -\frac{1}{2}e^t \end{bmatrix}$$

⑥  $C_1, C_2 = ? \quad Y(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$Y(0) = C_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + C_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ -\frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} C_1 + C_2 \\ -C_1 + C_2 - \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{aligned} C_1 + C_2 &= 1 \\ + \quad -C_1 + C_2 &= \frac{1}{2} \\ \hline 2C_2 &= \frac{3}{2} \\ C_2 &= \frac{3}{4} \\ C_1 &= \frac{1}{4} \end{aligned}$$

$$Y(t) = \frac{1}{4} \begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix} + \frac{1}{4} \begin{bmatrix} e^{3t} \\ e^{3t} \end{bmatrix} + \begin{bmatrix} 0 \\ -\frac{1}{2}e^t \end{bmatrix}$$